# **Dynamic Travel Behaviour:**

Findings of a stated adaptation experiment and modelling framework

Dimitrios Pappelis Maria Kamargianni Emmanouil Chaniotakis











# Introduction













Within-day Choice

Action





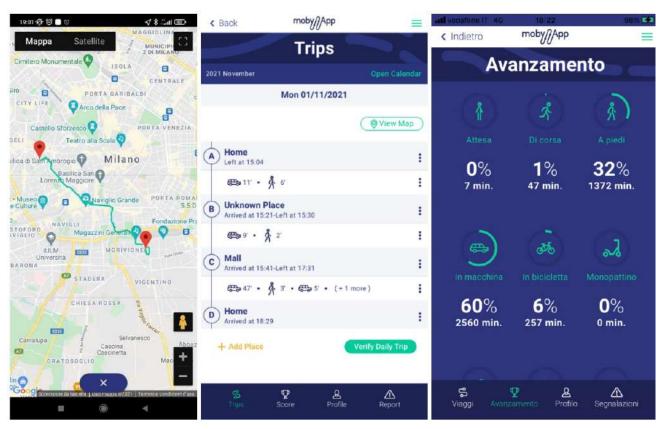
**Pre-day Plan** 

**Prior** 





# **Methodology – Data Collection**



Moby App (HARMONY project)

### **Revealed preference**

- Habitual activities
- Tracked travel patterns

### Stated adaptation

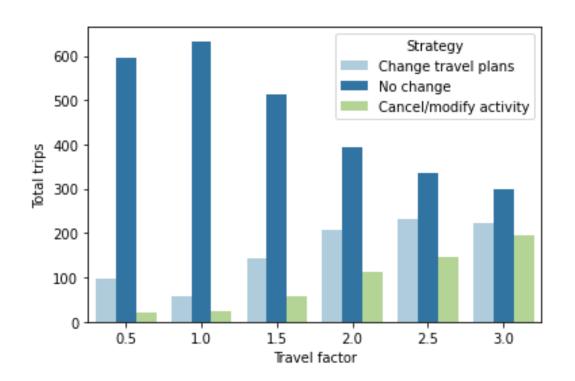
- Within-day re-evaluation
- Day-to-day learning
- Feedback/response quality

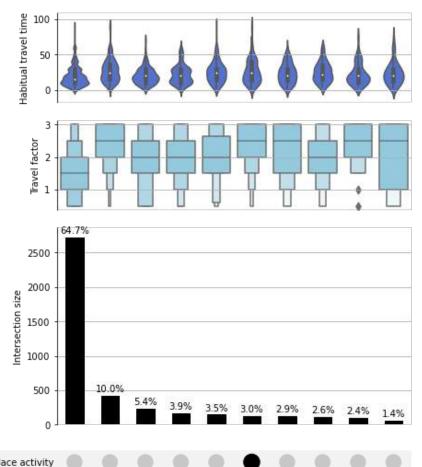
### **Application**

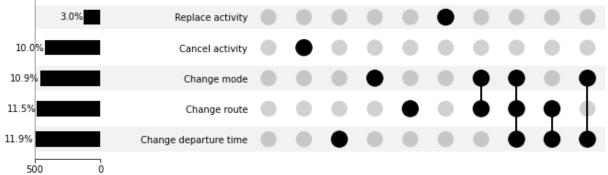
- **Turin**: 351 individuals 4212 observations
- Oxfordshire: 330 individuals 3960 observations



# **Exploratory Analysis**Resistance to change, mental effort









# Rational Expectation – Dynamic Hybrid Choice Model

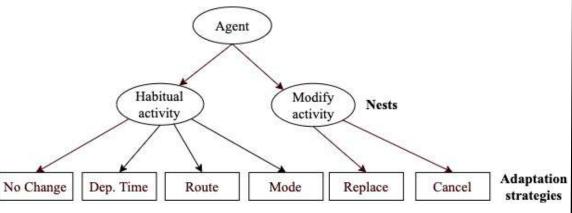


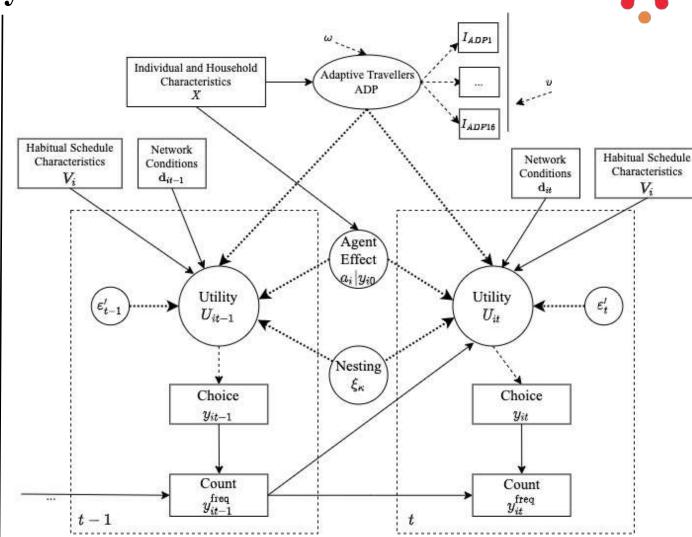
### Travel demand shift under information provision

Pandas Biogeme (Bierlaire)

### **Significant factors**

- Past actions and experience
- Travel time fluctuation
- Number of opportunities
- Activity type characteristics



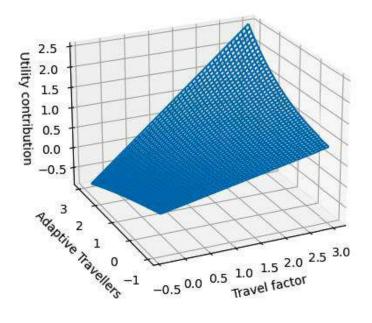


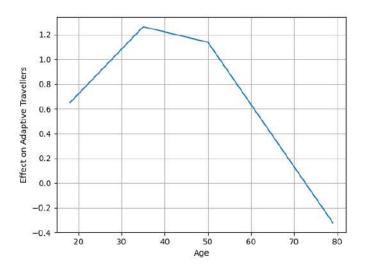


# **Latent Variable – Adaptive Travellers**

Indicato	rs of Adaptive Travellers	Mean	SD
I <sub>ADP1</sub>	It is very important for me to have short travel time to my main activities	5.76	1.33
I <sub>ADP2</sub>	I am willing to depart earlier or later if it can reduce my travel time	4.95	1.66
I <sub>ADP3</sub>	I would like to have flexible working hours to avoid rush hour commute	5.38	1.53
I <sub>ADP4</sub>	I would like to have remote work options to avoid rush hour commute	4.97	1.89
I <sub>ADP5</sub>	I would prefer working from home instead of commuting	4.72	1.97
I <sub>ADP6</sub>	I acquire travel information from my phone, as I am sure of their reliability	4.67	1.50
$I_{ADP7}$	I acquire travel information from my phone when I go somewhere I have never been before	5.35	1.50
I <sub>ADP8</sub>	I would acquire travel information from my phone if I come across congestion on my route	5.40	1.50
I <sub>ADP9</sub>	I am willing to acquire travel information while en-route to my destination	5.39	1.53
I <sub>ADP10</sub>	I acquire travel information from mobile devices prior to my trip	5.09	1.64
I <sub>ADP11</sub>	I would feel lost if I run out of battery while travelling	5.00	1.76
I <sub>ADP12</sub>	When I encounter delays in my travel plans, it stresses me out	4.96	1.60
I <sub>ADP13</sub>	I always try to maximize the efficiency of my trips	5.96	1.28
I <sub>ADP14</sub>	Whenever I need to adapt my trip schedule, I try to imagine all potential options	5.17	1.40
I <sub>ADP15</sub>	I always try to choose what I consider the best mode for my trips	5.51	1.40
I <sub>ADP16</sub>	I always try to optimize the route I choose for my trips	5.63	1.33

Parameter	Value	t-test		
$\lambda_{ ext{MALE}}$	-0.24	-5.7		
λ <sub>AGE</sub> UNDER35	0.0361	6.14		
λ <sub>AGE 35-50</sub>	-0.00839	-2.06		
λ <sub>AGE OVER50</sub>	-0.0503	-6.81		
λ <sub>HIGHEREDU</sub>	0.415	6.3		
$\lambda_{\text{LICENCE}}$	0.287	6.18		
$\lambda_{PUBTRAN}$	0.303	3.82		





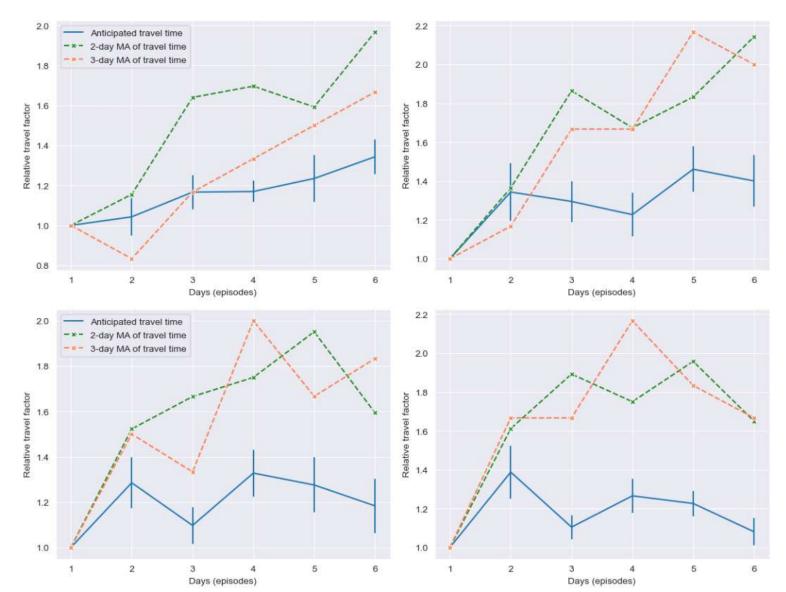




# **Rational inattention - Motivation**

# **Day-to-day learning**

- Resistance to change, inertia
- Sluggishness in response
- Prior 'magnet effect'



# **Rational Inattention**

Problem Formulation (Sims, Matejka, et al.)







Objective function:

$$\max_f \int U(y,x) f(y,x) dx dy - C(f)$$

Bayesian rationality:

$$\max_{f} \int U(y,x) f(y,x) dx dy - C(f)$$
 subject to 
$$\int f(y,x) dy = g(x), \ \forall x$$

Cost of information:

$$C(f) = \lambda \cdot I(y;x) = \lambda \cdot [H[g(x)] - E[H[x|y]]$$

Entropy measurement:

$$H[g(x)] = -\int g(x)log \ g(x)dx$$

General solution:

Continuous choice 
$$o f(y|x) = rac{p(y)e^{U(y,x)/\lambda}}{\int_z p(z)e^{U(z,x)/\lambda}dz}$$

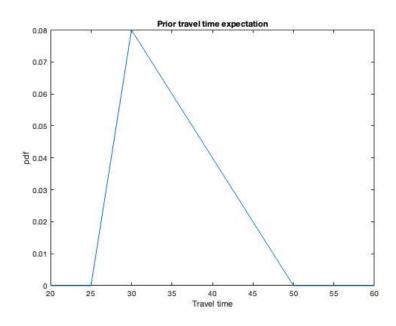
Discrete choice 
$$o P(i|x) = rac{e^{rac{U(i,x)+a(i)}{\lambda}}}{\sum_{j=1}^N e^{rac{U(j,x)+a(j)}{\lambda}}}$$



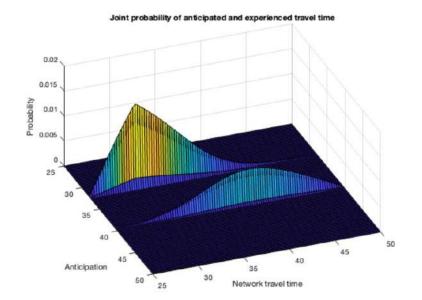
# Travel time anticipation

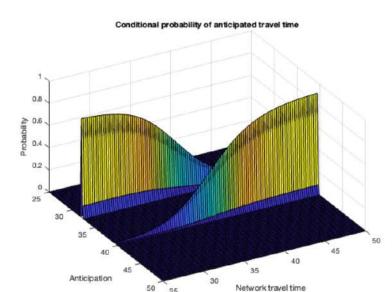
$$U(y,x) = -b(y-x)^2$$
 RI  $\to f(y|x)$  chosen optimally perfect information  $\to y = x$ 

no information  $\rightarrow y = E[g(x)]$ 

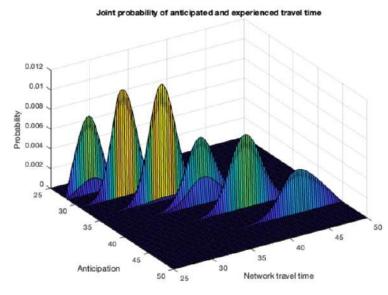


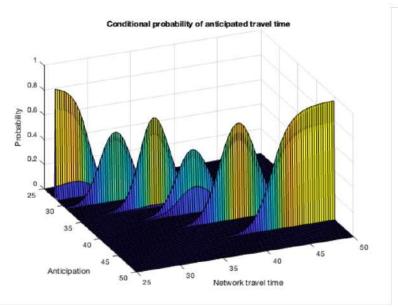






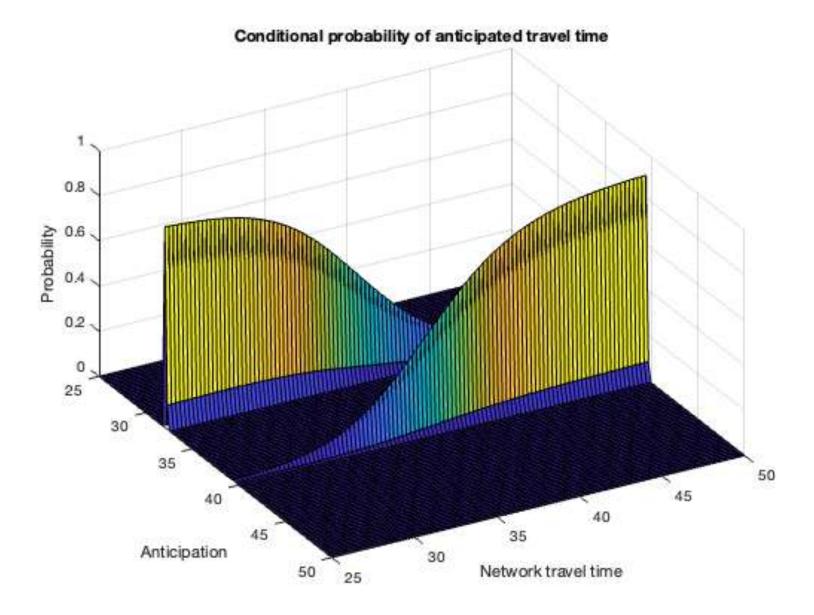
### $\lambda = 0.005$





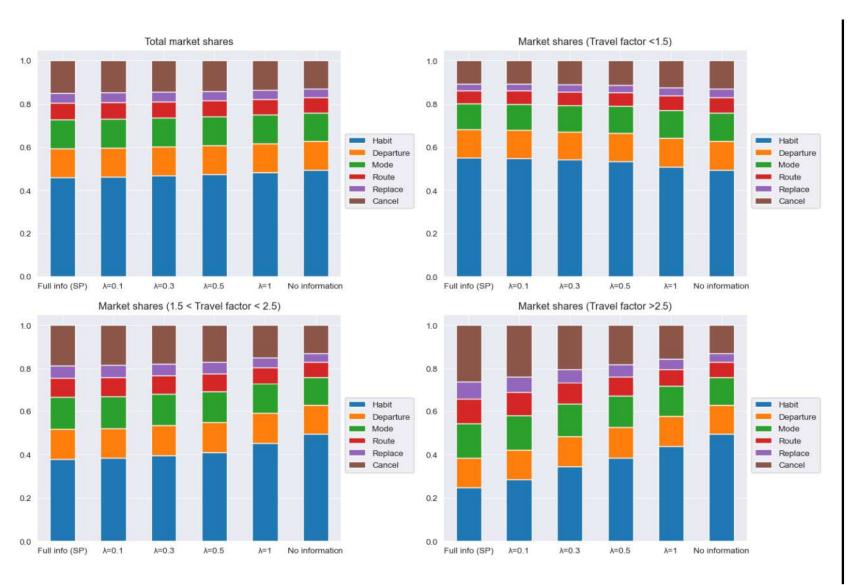








# **Empirical effect**





- Market share simulation with or without travel time inattention
- Discrepancy in prediction, especially for rare occurrences of the travel time distribution
- Underreaction but also overreaction 'mistakes'
- Importance of quantifying the information cost





# **Future Work**

## 1. Integration of dynamic demand shift model in within-day simulation

• Increased realism, personalization for menu set generation

## 2. Further exploration of RI in transportation phenomena

- Few studies with mostly theoretical contributions (Fosgerau)
- Forward-looking dynamic extensions

### 3. Data collection-estimation

- Joint measurement of belief, world, attention (signal), action
- Implications of general equivalence with RUM (Fosgerau)

### 4. Insights from observational / RP data

- What are we actually capturing? More than preferences?
- How to separate utility and priors/information cost?
- Market shares could be used as the priors (Caplin, Habib)

# 5. Application in other demand/supply models within transportation

• Travel information provision, adaptive ticket/toll pricing, service frequency



# **Conclusion**



"In an information-rich world, the wealth of information means a dearth of something else: a scarcity of whatever it is that information consumes. What information consumes is rather obvious: it consumes the attention of its recipients. Hence a wealth of information creates a poverty of attention and a need to allocate that attention efficiently among the overabundance of information sources that might consume it."

Herbert A. Simon (Nobel Laureate 1978)





Thank you!

		CONTRACTOR CONTRACTOR OF THE TOTAL		Static						(frequency)		and the second second	
	ALCOHOL: THE STATE OF THE STATE			Mixed		Mixed		Multinomial		Mixed		Mixed	
Annual de la				ltinomial Logit	Nested Logit		Logit		Multinomial Logit		Nested Logit		
Parameter	Value	t-test	Value	t-test	Value	t-test	Value	t-test	Value	t-test	Value	t-test	
ASCDEPARTURETIME	-1.83	-14.5	-2.72	-12.7	-3.25	-9.97	-2	-13.9	-2.16	-11	-2.13	-10.8	
ASCMODE	-2.1	-19.8	-2.63	-13.7	-3.78	-14.3	-2.45	-19.2	-2.5	-17.4	-2.49	-17.4	
ASCROUTE	-3.14	-21.2	-3.3	-18.7	-3.71	-16.8	-3.1	-19.2	-3.17	-18.1	-3.16	-18.1	
ASCREPLACE	-4.11	-19.2	1.05	4.12	-6.15	-13.9	-4.07	-17.	-4.74	-12.4	-4.87	-12.4	
ASCCANCEL	-2.32	-19	-3.91	-12.3	-4.63	-14.2	-2.86	-18.8	-3.72	-13.5	-3.81	-13.4	
ASCNOCHANGE	0.0	2	0.0	Ψ.	0.0	125	0.0	2	0.0		0.0	( <del>4</del> 4)	
βwork, nochange	-0.579	-6.89	-0.571	-5.91	-0.776	-4.17	-0.391	-4.25	-0.432	-4.16	-0.418	-4.12	
BWORK, CANCEL	-1.09	-7.36	-1.14	-5.69	-1.57	-4.56	-0.728	-4.52	-1.08	-4.23	-1.04	-4.05	
βBASETIME, NOCHANGE	-0.582	-12	-0.621	-9.89	-0.853	-7.73	-0.433	-8.31	-0.485	-7.46	-0.469	-7.32	
β <sub>ALT,MODES,MODE</sub>	0.152	6.31	0.14	5.08	0.279	4.3	0.0869	3.15	0.0985	3.39	0.351	3.38	
BALT, ROUTES, ROUTE	0.354	7.05	0.422	7.26	0.417	5.67	0.284	5.09	0.29	5.02	0.293	13.6	
BALT, DESTIN, REPLACE	0.356	6.26	0.355	6.17	0.459	4.15	0.283	4.68	0.349	4.27	0.351	4.24	
βtimediff, departure time	0.701	7.67	0.636	6.11	0.998	8.27	0.829	8.26	0.857	8.06	0.844	7.97	
βtimediff,mode	0.809	12.4	1.05	12.5	1.26	14.5	1.08	14.4	1.1	13.7	1.09	13.6	
βτιμεdiff, ROUTE	1.09	12.2	1.05	11.6	1.43	13.8	1.23	12.8	1.25	12.4	1.23	12.3	
β <sub>TIME</sub> DIFF, REPLACE	1.36	10.3	1.45	10.2	1.97	12	1.6	11.5	1.68	11	1.76	11.1	
βTIMEDIFF, CANCEL	1.31	17.1	1.77	16.2	2.16	18.5	1.69	19.1	1.94	17.5	1.97	17.4	
PFREQ,TRAVEL	0.0		0.0	75	0.0		1.25	26.5	1.19	21.1	1.2	21.2	
PFREQ.ACTIV	0.0	22	0.0	122	0.0	323	1.26	19.1	0.639	4.88	0.628	4.77	
PFREQ.NOCHANGE	0.0	5T	0.0	75	0.0		0.4	13.1	0.352	9.49	0.355	9.66	
GDEPARTURETIME	0.0	ie.	-1.18	-5.39	-2.44	-8.53	0.0	=	0.519	1.72	0.475	1.4*	
G <sub>MODE</sub>	0.0	42	1.86	8.02	2.13	12.5	0.0	2	0.0073	0.041*	0.0023	0.013	
σ <sub>ROUTE</sub>	0.0	17	0.0	3	0.0		0.0	-	0.0	(100 to 100 to 1	0.0	gradient (Section 1996) Section (Section 1996)	
GREPLACE	0.0	=	1.05	4.12	1.4	4.3	0.0	=	1.14	4.57	0.782	2.19	
GCANCEL.	0.0	-	2.77	11.2	2.19	8.99	0.0	Ø.	0.519	6.87	1.35	4.87	
ONOCHANGE	0.0	÷	0.515	3.03	1.47	13.8	0.0	-	0.398	2.4	0.323	1.64*	
OMODIFY	0.0	12	0.0	22	1.38	4.98	0.0	2	0.0	2	1	4.34	
<b>О</b> НАВІТ	0.0	-	0.0	=	0.0		0.0		0.0	-	0.0	SEANCH SEE	
Nb of observations	5507	FA	10	10	8/	25	4212	10	1575)	- CT	3	ē.	
L(0)							173.496						
Nb. of parameters	16		21		22		19		24		25		
AIC	8754.114		8169.515		7536.669		7348.235		7328.241		7325.476		
L(β) -4361.057				-4063.57 -3746.335			-3655.118			-3640.12		-3637.738	
Likelihood ratio test (within)	594.974(>11.07) 634.47(>3.84)					29.996(>11.07) 4.764(>3.84)							
Likelihood ratio test (across)		55 1.57 14 12.57						1411.878(>7.81) 846.9(>7.81) 217.194(>7.81)					